## Dependent Sources and Amplifiers

## Review

# - Nonlinear circuits - can use the node method <br> <br> - Small signal trick resulted in linear <br> <br> - Small signal trick resulted in linear response 

 response}

## Today

- Dependent sources


## - Amplifiers

## Reading: Chapter 7.1, 7.2

## Dependent sources

## Seen previously

Resistor



$$
i=\frac{v}{R}
$$

$\begin{array}{ll}\text { Independent } \\ \text { Current source } & +\quad- \\ \rightarrow\end{array}$

## 2-terminal 1-port devices

New type of device: Dependent source

E.g., Voltage Controlled Current Source Current at output port is a function of voltage at the input port

# Dependent Sources: Examples 

## Example 1: Find V

## independent current <br> source



$$
V=I_{0} R
$$

## Dependent Sources: Examples

Example 2: Find V

## voltage controled current source



## Dependent Sources: Examples

## Example 2: Find V

## voltage <br> controled <br> current <br> source


$V=I R=\frac{K}{V} R$
or $\quad V^{2}=K R$
or $\quad V=\sqrt{K R}$

$$
\begin{aligned}
& =\sqrt{10^{-3} \cdot 10^{3}} \\
& =1 \text { Volt }
\end{aligned}
$$

## Another dependent source example



Find $v_{O}$ as a function of $v_{I}$.

## Another dependent source example



$$
\begin{aligned}
i_{D} & =f\left(v_{I N}\right) \\
\text { e.g. } \quad i_{D} & =f\left(v_{I N}\right) \\
& =\frac{K}{2}\left(v_{I N}-1\right)^{2} \text { for } v_{I N} \geq 1 \\
i_{D} & =0 \quad \text { otherwise }
\end{aligned}
$$

Find $v_{O}$ as a function of $v_{I}$.

## Another dependent source example



Find $v_{O}$ as a function of $v_{I}$.

## Another dependent source example

$$
\begin{aligned}
& \text { KL } \\
& -V_{S}+i_{D} R_{L}+v_{O}=0 \\
& v_{O}=V_{S}-i_{D} R_{L} \\
& v_{0}=V_{S}-\frac{K}{2}\left(v_{I}-1\right)^{2} R_{L} \quad \text { for } v_{I} \geq 1 \\
& v_{O}=V_{S}
\end{aligned}
$$

## Hold that thought

## Next, Amplifiers

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### 6.002 - Fall 2002: Lecture 8

## Why amplify?

## Signal amplification key to both analog and digital processing.

## Analog:



Besides the obvious advantages of being heard farther away, amplification is key to noise tolerance during communcation

## Why amplify?

## Amplification is key to noise tolerance during communcation

## No amplification



## Try amplification



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## Why amplify? Digital:

## Static discipline requires amplification! Minimum amplification needed:



## An amplifier is a 3-ported device, actually

## Power port

## Input port



Output
port

We often don't show the power port.
Also, for convenience we commonly observe "the common ground discipline."
In other words, all ports often share a common reference point called "ground."


## How do we build one?

## Remember?



KV

$$
\begin{gathered}
-V_{S}+i_{D} R_{L}+v_{O}=0 \\
v_{O}=V_{S}-i_{D} R_{L}
\end{gathered}
$$



$$
v_{O}=V_{S}-\frac{K}{2}\left(v_{I}-1\right)^{2} R_{L} \quad \text { for } v_{I} \geq 1
$$

$$
v_{O}=V_{S} \quad \text { for } v_{I}<1
$$

Claim: This is an amplifier

## So, where's the amplification?

## Let's look at the $v_{O}$ versus $v_{I}$ curve.

$$
\begin{aligned}
& \text { e.g. } \quad V_{S}=10 \mathrm{~V}, \quad K=2 \frac{m A}{V^{2}}, \quad R_{L}=5 \mathrm{k} \Omega \\
& \begin{aligned}
v_{O}= & V_{S}-\frac{K}{2} R_{L}\left(v_{I}-1\right)^{2} \\
= & 10-\frac{2}{2} \cdot 10^{-3} \cdot 5 \cdot 10^{3}\left(v_{I}-1\right)^{2} \\
v_{O} & =10-5\left(v_{I}-1\right)^{2}
\end{aligned}
\end{aligned}
$$


$v_{I}$

$$
\frac{\Delta v_{O}}{\Delta v_{I}}>1
$$

## Plot $v_{O}$ versus $v_{I}$

$$
v_{O}=10-5\left(v_{I}-1\right)^{2}
$$



## Measure $v_{O}$.

## One nit



Mathematically,

$$
v_{O}=V_{S}-\frac{K}{2} R_{L}\left(v_{I}-1\right)^{2}
$$

So is mathematically predicted behavior

## One nit



However, from

$$
i_{D}=\frac{K}{2}\left(v_{I}-1\right)^{2} \quad \text { for } v_{I} \geq 1
$$



For $v_{O}>0, V C C S$ consumes power: $v_{O} i_{D}$ For $v_{o}<0$, VCCS must supply power!

## If VCCS is a device that can source power, then the mathematically predicted behavior will be observed -



If VCCS is a passive device, then it cannot source power, so $v_{O}$ cannot go -ve. So, something must give!

## Turns out, our model breaks down.

Commonly $i_{D}=\frac{K}{2}\left(v_{I}-1\right)^{2}$
will no longer be valid when $v_{O} \leq 0$. e.g. $i_{D}$ saturates (stops increasing) and we observe:


